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Objectives and Activities

The main objective of AMM is to contribute to mechanical design at all levels starting from academic research to industrial initiatives, thereby enhancing the quality and reliability of indigenous machines. With this in view, AMM organises the International & National Conference on Machines and Mechanisms, iNaCoMM, and the workshops on Industrial Problems on Machines and Mechanisms, IPRoMM regularly.

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Message from the Editor-in-Chief

Volume 10 No.3 July 2018 issue is being published amidst the rainy season with the lush green surroundings. While in Kerala there is a devastating flood and also flood situation in different parts of India, there are some areas where there is less than average rain. True, there is wide diversity existing in India!

This issue of the Bulletin of the Association for Machines and Mechanisms (AMM) is also brought out by the continuing Editorial Board Members. This issue of the Bulletin is published with **Dr. Ranjit Kumar Barai**, (**ZVP**, **East**) taking steps to bring out this issue. The Editor-in-Chief takes the sole responsibility for slightly late publication of this issue and he does not wish to cite any excuse behind it. He is really sorry for the same.

An article bearing the title, **"Development of a Magnetic Reciprocating Engine"** is contributed mainly by a group of students of Department of Mechanical Engineering, Kalyani Government Engineering College, Kalyani. Hope readers would find the article interesting that outlines an innovative work.

Information Brochures of a number of forthcoming events is included in this issue as usual. Hope AMM community will participate in large number to make the 5th IFToMM Asian Mechanisms and Machine Science Conference 2018 being organised in Bangalore on December 18-19 2018 a grand success.

AMM members and others are requested to send contribute articles and technical briefs to the editorial team for October 2018 issue. Constructive suggestions, comments for improvement of the Bulletin of the AMM are most welcome.

On behalf of the Editorial Team of the Bulletin of AMM, I thank all concerned for their support, good wishes and suggestions for bringing out of this Bulletin.

> Prof. Santanu Das Editor-in-Chief

The AMM headquarter is currently located at the Department of Engineering Design, IIT Madras. A new set of office bearers have taken charge of the affairs of AMM. AMM invites both individual and corporate membership from Indian academia, research organizations and industry. Membership benefits and other information about AMM are available at <u>www.ammindia.org</u>. The body of Zonal Vice Presidents (ZVPs) is active over the past several years with representations from the four corners of the country. They are playing the role of nodal agencies so as to decentralise the AMM official activities and to organise workshops under the aegis of AMM to popularise the mechanism science in their respective regions. They also form the editorial team of this news bulletin. AMM invites contributory articles from its members and others working in the various fields of mechanisms science for this quarterly news bulletin. Interested people can contact the editorial team.

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Good decisions come from experience. But experience comes from bad decisions. This is life; so, never regret. Learn from mistakes and GO AHEAD.

--- Anonymous

Development of a Magnetic Reciprocating Engine

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1. INTRODUCTION

21st century is an era of innovation, science and technology. However, in case of vehicle industry, traditional fuels are still widely used in this innovative era. As a result, environment gets polluted. Though electrical engines are good substitutes for diesel and petrol engines, these are not much effective. So the concept of Magnetic Reciprocating Engine may overcome the above mentioned problems and may be the future of vehicle industry.

2. DESIGN AND WORKING PRINCIPLE

Keeping the above mentioned issues in mind, an engine is designed and developed in this work. It is easy to manufacture compared to the traditional engine. It is also eco-friendly and has a broad future scope of modification. Working principle of this engine is totally based upon the concept of magnetic repulsion and attraction property.

In Fig.1, it is shown that there is an electromagnet which is fixed at its mean position. A movable structure, which has two permanent magnets at both ends, should move along the vertical axis of the electromagnet. Behind this, a circuit (Fig.2) is connected with the ends of copper winding around electromagnet. This circuit has a vital role to change the direction of current after a certain interval. It contains a SMPS (Switch mode power supply), four solid state relay switches, an Arduino board, a photoelectric sensor, and a breadboard. This circuit is designed to control the polarity of electromagnet by changing the direction of current w.r.t. the piston position. A photoelectric sensor is used to detect the position of piston and sense the data to send it to Arduino board which controls the relay switch and changes the direction of current accordingly. Top view of the engine is shown in Fig.3.

Working principle of this engine has to be explained with help of Fig 1. At first, it is supposed that the electromagnet has North Pole at upper end and south at bottom end. At the same time, permanent magnet 1 (PM-1) has North Pole at bottom end and permanent magnet 2 (PM-2) has North Pole at its upper end. As a result, electromagnet repels PM-1 and attracts PM-2 simultaneously. This way piston will have an upward movement.



Fig.1 Side view of the Engine



Fig.2 Circuit



Fig.3 Top view of the engine

When the PM-2 comes closer to electromagnet, current in Copper winding has to be reversed. So the previous pole setup of electromagnet gets reversed but poles of PM-1 and PM-2 remain the same. So, in the same manner, PM-2 is repelled by electromagnet, and PM-1 is attracted simultaneously, and the piston will move downward. This way, piston will have a continuous reciprocation if this process will occur in a cyclic manner. A slider crank mechanism is attached with one end of the piston that converts this reciprocating motion into rotary motion. A flywheel is fitted with the crank shaft as usual.

3. MATERIAL USED

A soft iron core is used as electromagnetic core which is wrapped by several number of turns of copper wire co-axially, and a Sintered Neodymium (Nd₂Fe₁₄B) Magnet is used as permanent magnet. All other components of this design are made of Aluminium. Neodymium magnets are the strongest type of permanent magnet commercially available.

4. CALCULATIONS

Using the equations, torque is calculated with the change in crank angle. It is found that there are two power strokes in 360 degrees of crank rotation and the graph between angle of rotation and mean torque is given in Fig.4. Isometric schematic view of the engine is given in Fig.5.

$$\begin{split} F &= (\mu_0/4\pi) \; (q_1 q_2/x^2) \\ \text{Or, } F &= (\mu_0/4\pi) \; q_1 q_2 \left((1/\;(80\!+\!x)^2) + (1/\;(80\!-\!x)^2)) \right) \\ \text{Or, } T &= r \; F = r \; (\mu_0/\;4\pi) \; q_1 q_2 \left((1/(80+x)^2) + (1/\;(80\!-\!x)^2)) \right) \end{split}$$

where, $x = r (n - \sqrt{(n^2 - \sin^2 \theta)}) + r (1 - \cos \theta) q_1 = (N I A / L)$

Input= (36 V) (15 A) = 540 W $T_{mean} = (J(T d\theta))_{(0,2\pi)} / (2\pi)$ Output = (2 π N T_{mean}) / 60 So, Efficiency = $\eta = (2\pi$ N T_{mean}) / (60x540)

where,

F= Force between two magnetic dipole $q_1 \& q_2$ = pole strength of electromagnet and permanent magnet T= Torque acted upon crank X= Displacement of piston= f(angle made by crank with horizontal) N= L/r L= length of connecting rod N= No. of turns in electromagnet I= Current passing through Cu wire T_{mean}= Mean torque



Fig.4 Plot of torque with crank angle obtained through simulation



Fig.5 Schematic Isometric view of the assembly

5. POSSIBLE APPLICATIONS

As its efficiency is thought of to be higher compared to an I.C. engine or Electrical engine, it can be used in automobile or industrial applications. In valve controlling system of IC engine, the principle of this engine can be employed. It can also be used instead of pneumatic actuators, and in the field where reciprocating concept plays a vital role, like reciprocating pump and compressor.

6. IMPLEMENTATION ISSUE

During fabrication of this engine, it should be noticed that the position of electromagnet will be perfectly constrained with the help of a clamping device otherwise the device becomes unstable due to vibration caused by reciprocation. Permanent magnet should be properly and tightly located at their position. Connection should be properly done and there should be a leak proof cover of magnetic proof material so that there will be no flux loss from the system.

REFFERENCE

- [1] https://en.wikipedia.org/wiki/Neodymium_magnet, accessed on March 06 2018.
- [2] P. Hota, M. Rathore and D. Shaikh, Magnetic repulsion piston engine, International Journal of Science and Research, Vol. 4, No.12, pp.338-344, 2015.
- [3] S. Menta, V.Konduru and S.V. Kalahsti, Magnetic piston engine, International Journal of Mechanical Engineering and Robotic Research, Vol.3, No.1, pp.59-66, 2014.
- [4] S. Dhangar, A. Korane and D. Barve, Magnetic piston operated engine, International Journal of Advanced Research in Science and Engineering, Vol. 4, No.6, pp.219-225, 2018.
- [5] https://www.slideshare.net/vishalsatsangi/magnetic-repulsion-piston-engine, accessed on July 5 2018.

Forthcoming Events



Conference Website: www.robotics2018.tuiasi.ro

General information:

It is our pleasure to invite you to ROBOTICS 2018, organized by "Gheorghe Asachi" Technical University of Iasi, Romania, during September 20 - 21, 2018. The conference aims at bringing together under a unique forum, scientists from academia and industry to discuss the state of the art and the new trends in robotics and to present recent research results and prospects for development in this rapidly evolving area.

All materials must be written in English. Submitted papers will undergo a peer review process, coordinated by the International Program Committee. All the selected and presented papers will be published in IOP Conference Series: Materials Science and Engineering (ISI Web of Science).

Organized by:

"GHEORGHE ASACHI" TECHNICAL UNIVERSITY OF IASI FACULTY of MECHANICAL ENGINEERING FACULTY of AUTOMATIC CONTROL AND COMPUTER ENGINEERING

With the support of: ROBOTICS SOCIETY of ROMANIA - SRR

Important deadlines:

March 18, 2018:	Submission of papers
May 15, 2018:	Notification of acceptance
June 15, 2018:	Final camera ready manuscript and registration of at least one of
	the authors
September 20 – 21, 2018:	Conference

For any questions please contact the organizers at <u>robotics2018@tuiasi.ro</u>

Forthcoming Events

FIRST ANNOUNCEMENT AND CALL FOR PARTICIPATION



4th Students International Olympiad on MECHANISM AND MACHINE SCIENCE

October 24-26, 2018, Lima, Peru



SIOMMS 2018 www.pucp.edu.pe/siomms2018

The **Pontificia Universidad Católica del Perú** is pleased to invite university teams to participate in the 4th Students International Olympiad on Mechanism and Machine Science (SIOMMS) that will be held on October 24-26, 2018. This fourth global Olympiad will be arranged following the decision of the Executive Council of International Federation for the Promotion of Mechanism and Machine Science (IFTOMM). It will follow the previous ones in Izhevsk State Technical University (ISTU), Izhevsk, Russia in 2011, Shanghai Jiao Tong University (SJTU), Shanghai, China in 2013 and Universidad Carlos III de Madrid, Spain in 2016.



PROBLEM TOPICS

- Structural analysis and synthesis of mechanisms
- Kinematics of flat mechanisms
- Force analysis of mechanisms
- Kinematic analysis of cam
- mechanisms
- Gearings (kinematics, geometry, efficiency)
- Adjustment of dynamic
- characteristics, mechanical
- governors
- Balancing of rotating masses

LANGUAGE

The working language of the Olympiad is English.

TEAMS

Teams consisting of three (3) bachelor and master students and one (1) or more tutors are invited to take part in the Olympiad. Each university may send only one team. The choice of students for each university team may be conducted on the basis of its own local selection competition.

LOCAL ORGANIZING COMMITTEE Pontificia Universidad Católica del Perú

- Jorge Rodríguez Hernández
- (Chair).
- Jorge Alencastre Miranda (Vice-Chair).
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- Daniel Lavayén Farfán.
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- E. Krylov, Russia.
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- L. Zentner, Germany.
- M. Ceccarelli, Italy.
- P. Flores, Portugal.
- B. Corves, Germany.
- J. Alencastre, Peru.
- O. Penisi, Argentina.
- V. Petuya, Spain.
- C. López Cajún, México.
- · A. Pérez-Gracia, USA.

CONTACT PERSON

Jorge Rodríguez Hemández. Mechanical Engineering section Av. Universitaria 1801, San Miguel, Lima 32. Peru crodrig@pucp.edu.pe

REGISTRATION FEES

The registration fee is 150 USD for each participant, which covers the participation in the Olympiad, meals and social program. The accommodation has to be covered by the participants extra. The payment will be detailed by website.

IMPORTANT DATES

Submission of electronic application form: March 28, 2018. Registration fee payment: June 30, 2018.

APPLICATION

The application will be via website.

TRANSPORTATION

Lima is the capital city of Peru and is one of the most important cities of Latin America. Lima is located in the central coast, along the Pacific Ocean.

Lima has excellent public transport within the city and has a very modern airport in the port of Callao.

HOST CITY

Peru's capital has more than 10 million people, made up of different races of the world. The historic center of Lima was declared World Heritage Site by UNESCO. Lima is a city with great cultural diversity that is why there are a large number of museums. In Lima you will find everything you are looking for as cultures, adventures, beaches, dining,

T 626 2000 www.pucp.edu.pe/siomms2018 Campus principal: Av. Universitaria 1801, San Miguel - Lima 32, Perú





Call for Papers

15th IFToMM World Congress will be held in Krakow, Poland in June 30 – July 4, 2019. IFToMM World Congress is held every 4 years and is the largest congress on mechanism and machine science. It will provide opportunityfor researchers, scholars and students with interests in the theory and practice of mechanisms and machines for new ideas, sharing experiences, and discussing future developments. We hereby would like to extend our sincere welcome to you and to ensure all of you a wonderful congress and a memorable visit during your stay in Krakow during 2019 IFToMM World Congress!

is available in the congress webpage

15 August, 2018

15 January 2019

15 February, 2019

15 March, 2019

31 March, 2019

31 March. 2019

30 June - July 4, 2019

CONGRESSLOCATION

15 November, 2018

PAPERSUBMISSION

All papers must be submitted electronically and they will be reviewed. Authors are

requested to submit a full length paper, 4 pages (minimum) to 10 pages (maximum). The abstracts are NOT acceptable. The format will follow the IFToMM template that

IMPORTANTDATES

Registration Start

Camera ready

Full Paper submission deadline

Notification on final paper Acceptance

Deadline for paying fee of presenting authors

TC acceptance of the paper

Final Full paper submission

IFToMM Congress

Sincerely yours Organizing Committee

TOPICSOFTHECONGRESS

Papers are welcome on the general areas of the theory and practice of machines and mechanisms, but not limited, to the topics of the IFTOMM Technical Committees and Permanent Commissions, namely.

Biomechanical engineering
Computational hiermatics
Design methodology
Biomechanical engineering
Computational kinematics
Design methodology
Dynamics of machinery
Dynamics of machinery
Dynamics of machinery
Education
Gearing and transmissions
History of MMS
Unlage and mechanical controls
Micromechanisms
Multibody dynamics
Micromechanisms
Robordis
Rotar dynamics
Standardization of terminology
Sustainable energy systems
SiTransportation machinery
Tirabology
Wioration

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PRESENTATION AND PROCEEDINGS

The official language is English. Registered participants will receive one Digital Proceedings. Proceedings will be indexed in WoS, SCOPUS (will be confirmed later).

Conference proceedings will be published as an e-book by Springer which is indexed in Web of Science, Scopus and others.

The conference will take place in the Auditorium Maximum of the Jagielonian University. Krakow is the capital of Malopolska province located on the south of Poland, large academic and cultural centre and is one of the most visited cities in Poland. There are numerous historical monuments, good hotels, restaurants and recreational opportunities. It is not a simple task to describe the unique character of Krakow to those who still have not had the opportunity to visit this city. This uniqueness is primarily due to the rare cultural hertage embodied within the city walls. Here, in the year 1000, a Roman Catholic bishopric was founded. Here, the residential royal castle was constructed on the Wavel Hill, becoming the site for the coronations and burals of Kings, as Krakow was the capital of Poland from the 11th to 17th century. ACCOMODATION

A variety of hotels with special rate in eirent standards with the room rate ranging from EUR0 50 to EUR0 150 will be listed in the IFToMM 2019 website.

TRAVELINFORMATION

Krakow airport is located about 10 km from the city centre and has a number of direct flight connections with major European airports (Munich, Frankfurt, Vienna, Berlin, Paris, Brussels, London, and others).

Burssels, London, and others). International airport in Kraków (10 km from the city) http://www.krakowairport.pi/en International airport in Katowice (60 km from the city) http://www.katowice-airport.com

Contact: Prof Tadeusz Uhl - Chair of the OC for 2019 WC

AGH University Science & Technology, Kraków, Poland. e-mail: congress@iftomm2019.com www.lftomm2019.com

Registratiom type	(before 31 March)	(after 81 March)	registration	
Delegate from FToMM MO	500 EUR	600 EUR	650 EUR	
Delegate from 1on - IFToMM MO	550 EUR	650 EUR	700 EUR	
Student	350 EUR	400 EUR	450 EUR	
Accompanying person	200 EUR	250 EUR	300 EUR	

www.iftomm2019.com





Editorial Board

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